

# Methods for multi-loop computations

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# Lecture II

## Special Functions

▶ **Introduction:**

1. Analytic properties of the Scattering amplitude

▶ **Special Functions 1. Iterated integrals**

1. From **polylogarithms** to **GHPLs**
2. Chen Iterated integrals
3. Transcendentality in repeated integrations

▶ **Special Functions 2. Elliptic Functions**

1. How to introduce a concept of transcendentality ?
2. More questions than answers :-)

# Introduction

- ▶ Scattering amplitudes (SA) are **analytic functions** on the complex plane
- ▶ Analytical structure of SA is dictated by interplay of:
  1. Number of **independent scales**
  2. **Kinematical constraints**
- ▶ This goes into the **functions** needed to describe the result !
- ▶ Let's see what happens with **Vector Boson Pair Production**

## Vector boson pair (VBP) production - in massless QCD:

- ▶  $q \bar{q} \rightarrow \gamma \gamma$ 
  1. 2 independent scales:  $s + t + u = 0$
  
- ▶  $q \bar{q} \rightarrow Z \gamma / W^\pm \gamma$ 
  1. 3 independent scales:  $s + t + u = m^2 \rightarrow$  with linear kinematics!
  
- ▶  $q \bar{q} \rightarrow Z Z / W^\pm W^\pm$ 
  1. 3 independent scales:  $s + t + u = 2 m^2 \rightarrow$  with non-linear kinematics!
  
- ▶  $q \bar{q} \rightarrow Z W$ 
  1. 4 independent scales:  $s + t + u = m_Z^2 + m_W^2 \rightarrow \dots$

## VBP-production - What determines the complexity?

- ▶  $q \bar{q} \rightarrow \gamma \gamma$  ( All MIs computed in  $\approx$  2000 )
- ▶  $q \bar{q} \rightarrow Z \gamma / W^\pm \gamma$  ( All MIs computed in  $\approx$  2001 )
- ▶  $q \bar{q} \rightarrow Z Z / W^\pm W^\pm$  ( Planar MIs computed in 2013 )
- ▶  $q \bar{q} \rightarrow Z W$  ( Planar MIs computed in 2014 )

note that:

1. “Discovery” of **HPLs** came in 1999
2. Extension to **2d-HPLs** in 2001  $\rightarrow$  needed for 1 more scale in  $V \gamma$  !
3. **12 years** to “add no more scales”  $\rightarrow$  non-linear kinematics !

Fundamental step in order to complete a **multi-loop** computation:

Understand the **analytical properties** of functions that express the result!

### Special Functions:

1. Logarithms
2. Polylogarithms
3. Generalised Harmonic-Polylogarithms (GHPLs)
4. Chen iterated integrals
5. Elliptic functions
6. *Elliptic Polylogarithms (??)*

- ▶ Functions needed for VBP-production are the so-called **GHPLs**.
  - ▶ GHPLs are a special class of **iterated integrals**.
  - ▶ More **scales** or more complicated **kinematical constraints** influence the **analyticity structure** of these iterated integrals.
  - ▶ As long as they are GHPLs we can “handle them” ...
  - ▶ “Experience” shows that at some point iterated integrals are not enough.
    1. “too many” **internal masses**
    2. “too many” **loops**
    3. “more complicated cut-structure” of **non-planar integrals**
- **Elliptic Functions...** very little is known...



But let us go step by step and start with what we can do!

# Special Functions 1.

Iterated integrals (and mainly GHPLs !)

- ▶ Many classes of Feynman integrals, **once expanded in  $(d - 4)$** , seem to be naturally expressed in terms of iterated integrals → (see [Lecture 3](#)).
- ▶ This is true in particular when there are **no masses** in the loops → large range of applicability in **massless QCD!**
- ▶ Simplest example of iterated integrals are:  
**Multiple Polylogarithms (MPLs)** or  
**Generalised Harmonic Polylogarithms (GHPLs)**.

## What is an iterated integral ?

Given a set of integration kernels  $K_j(t)$  we can define:

$$\mathcal{I}(i; x) = \int_{x_0}^x K_i(t) dt ,$$

$$\mathcal{I}(j, i; x) = \int_{x_0}^x K_j(t) \mathcal{I}(i; t) dt$$

...

$$\mathcal{I}(i_n, \dots, i_1; x) = \int_{x_0}^x K_{i_n}(t) \mathcal{I}(i_{n-1}, \dots, i_1; t) dt$$

This objects appear as the “*natural choice*” to represent solution of Feynman integrals **once expanded in  $d - 4$** .

## Step 1. The Logarithm

The logarithm is a trivial example of iterated integral:

$$\log(x) = \int_1^x \frac{dt}{t}, \quad \log\left(1 - \frac{x}{a}\right) = \int_0^x \frac{dt}{t-a}, \quad \forall a \neq 0.$$

With the obvious consequence:

$$\frac{d}{dx} \log(x) = \frac{1}{x}, \quad \frac{d}{dx} \log\left(1 - \frac{x}{a}\right) = \frac{1}{x-a}, \quad \forall a \neq 0.$$

- **Important lesson:** differentiating the log we get *something easier!*

## Step 2. The Di-Logarithm (Spence's function)

Already at 1-loop it is clear that logs are not enough.

$$\text{Li}_2(x) = - \int_0^x \frac{dt}{t} \log(1-t) = \sum_{n=1}^{\infty} \frac{z^n}{n^2}, \quad \forall x \in \mathbb{C} - [1, \infty).$$

With the obvious consequence:

$$\frac{d}{dx} \text{Li}_2(x) = -\frac{1}{x} \log(1-x).$$

### ► Important lessons:

1. Differentiating the  $\text{Li}_2$  we get *something easier*  $\rightarrow$  the log !
2. The  $\text{Li}_2$  is an iterated integral with kernel  $1/t$  !

Soon the idea has been generalised to the so-called **classical polylogarithms**

$$\text{Li}_{n+1}(x) = \int_0^x \frac{dt}{t} \text{Li}_n(t), \quad \forall x \in \mathbb{C} - [1, \infty)$$

$$\text{Li}_1(x) = -\log(1-x).$$

With the obvious consequence:

$$\frac{d}{dx} \text{Li}_n(x) = \frac{1}{x} \text{Li}_{n-1}(x).$$

► **Important lesson:**

1. Differentiating the  $\text{Li}_n$  we get *something easier*  $\rightarrow$  the  $\text{Li}_{n-1}$  !
2. Is something missing??



How are the  $\text{Li}_n(x)$  built ?

1. We start with an **integration kernel**:

$$\text{Li}_1(x) = -\log(1-x) = \int_0^x dt K(t), \quad \text{with} \quad K(t) = -\frac{1}{t-1}.$$

2. We proceed then integrating on a **different** kernel

$$\text{Li}_{n+1}(x) = \int_0^x dt \hat{K}(t) \text{Li}_n(t), \quad \text{with} \quad \hat{K}(t) = \frac{1}{t}.$$

3. What happens **mixing up** the two kernels?

$$K_0(t) = \frac{1}{t}, \quad K_1(t) = \frac{1}{t-1}.$$

1. It makes sense to “mix” **all 3 possibilities**:

$$K_0(t) = \frac{1}{t}, \quad K_{+1}(t) = \frac{1}{t-1}, \quad K_{-1}(t) = \frac{1}{t+1}.$$

2. And define the following functions:

$$G(0, x) = \log(x) = \int_1^x dt K_0(t),$$

$$G(\pm 1, x) = \log(1 \mp x) = \int_0^x dt K_{\pm 1}(t).$$

3. And finally

$$G(a, \vec{n}, x) = \int_0^x dt K_a(t) G(\vec{n}, t), \quad \text{with } a = \{0, 1, -1\}.$$

These are the so-called **Harmonic Polylogarithms (HPLs)**.

## Generalisation → Generalised Harmonic Polylogarithms (GHPLs)

The **GHPLs** are defined allowing for any linear rational factor as Kernel !

1.

$$G(0; x) = \log(x), \quad G(a; x) = \log\left(1 - \frac{x}{a}\right), \quad \forall a \neq 0.$$

2.

$$G(\vec{0}_n; x) = \frac{1}{n!} \log^n(x), \quad G(a, \vec{n}; x) = \int_0^x \frac{dt}{t-a} G(\vec{n}; t)$$

3. Note that 'a' can also be a *function of other variables* ...

## Definitions

Given a GHPL  $G(\vec{n}; x)$  :

1.  $\vec{n}$  is said **index vector**.  $G(1, 0, -1, 1; x) \rightarrow \vec{n} = (1, 0, -1, 1)$
2. Number of elements of  $\vec{n}$  is said **weight**  $w$ .  
 $G(1, 0, -1, 1; x)$  has weight  $w = 4$ .
3. The weight is often called **degree of transcendentality** of the GHPLs.  
 $w = 4 \rightarrow$  **transcendality 4**.
4. Set of all indices is said **Alphabet**.  
Alphabet of HPLs is  $\{1, 0, -1\}$

## Important:

1. The index vector contains the **analytical structure** of the GHPLs.
2. The analytical structure of the **S-Matrix** goes into the **index vector**!
3. The more complicated is the **cut structure** the more complicated will be the **indices** of the GHPLs.

Many HPLs can be written as classical Polylogarithms:

$$G(1, 1; x) = \frac{1}{2} \log(1-x)^2, \quad G(0, 1; x) = -\text{Li}_2(x),$$

$$G(0, 1, 0; x) = 2 \text{Li}_3(x) - \log(x) \text{Li}_2(x), \dots$$

But obviously not all of them. First examples at **weight 4**:

$$\begin{aligned} G(-1, 0, 0, 1; x) &= \int_0^x \frac{dt}{t+1} \int_0^t \frac{du}{u} \int_0^u \frac{dv}{v} \int_0^v \frac{dw}{w-1} \\ &= - \int_0^x \frac{dt}{t+1} \text{Li}_3(t). \end{aligned}$$

All GHPLs up to weight 3 can be **always** written as **classical polylogarithms** !

## Properties of GHPLs:

1. **Shuffle algebra** (*true for iterated integrals*):

$$G(\mathbf{a}; x)G(b, c; x) = G(\mathbf{a}, b, c; x) + G(b, \mathbf{a}, c; x) + G(b, c, \mathbf{a}; x)$$

2. **Scale invariance:**

$$G(a_1, \dots, a_n; x) = G(\lambda a_1, \dots, \lambda a_n; \lambda x), \quad \forall \lambda \in \mathbb{C}, a_n \neq 0$$

3. **Cut structure:**

Whenever the variable  $x$  becomes **larger** than any of the indices the GHPLs develop an **imaginary part!**

$$G(a; x) = \ln(1 - x/a) \in \mathbb{R}, \quad \forall x \leq a.$$



## Two important values:

1.

$$\lim_{x \rightarrow 0} G(\vec{n}; x) = 0, \quad \forall \vec{n} \neq \vec{0}_n$$

2.

$$\lim_{x \rightarrow a} G(a, \vec{n}; x) \rightarrow \infty, \quad \forall \vec{n} \in \mathbb{C}^n$$

- ▶ **HPLs** have been found to be the *right set of functions* to express Feynman integrals depending on **two independent scales**.  
(with  $x$  some appropriate dimensionless ratio of the two...)
- ▶ This is true *almost independently* on the **number of loops**.

## Examples:

1. 1-,2-,3- and 4-loop **massive 2-point functions** in special kinematical configurations:  $\{p^2, m^2\}$ .
2. 1- and 2-loop **QED form-factor**:  $\{p^2, m_e^2\}$
3. 1-, 2-, 3-loop **4-point functions** in massless QCD with *on-shell legs*:  $\{t, u\}$  with  $s = -t - u$ .
4. many others...

In all these cases one can find an appropriate dimensionless combination of the two variables which transforms the result in only HPLs:

- ▶  $x = p^2/m^2$

- ▶  $x = (\sqrt{p^2 + 4m^2} - \sqrt{p^2})/(\sqrt{p^2 + 4m^2} + \sqrt{p^2})$

- ▶  $x = t/u$

- ▶ ...

What happens when there are **more independent scales**?

**2d-HPLs** are easiest example of GHPLs,  
introduced for dealing with **three-scale** process:

$$\gamma^*(p_4) \rightarrow q(p_1) + \bar{q}(p_2) + g(p_3), \quad s + t + u = p_4^2$$

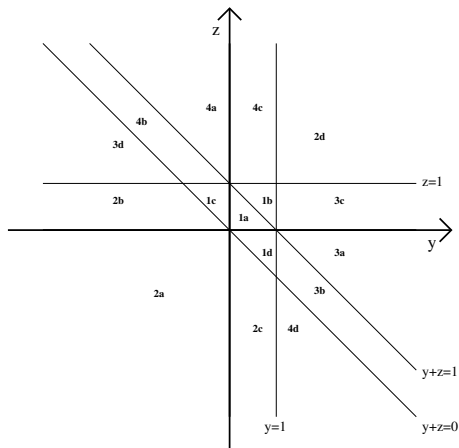
Depends on two dimensionless variables:

$$y = \frac{t}{p_4^2}, \quad z = \frac{u}{p_4^2}$$

1. We need **HPLs** of 1 variables:  $G(\{1, 0, -1\}; z)$
2. Plus **2d-HPLs** of the other, with **Alphabet**

$$G(\{1, 0, 1 - z, -z\}; y)$$

The indices represent the different **kinematical cuts**:  $\gamma^* \rightarrow q\bar{q}g$



In this case all cuts are **linear functions**!

Consider now **one more** external mass:

$$q(p_1) + \bar{q}(p_2) \rightarrow W(q_1) + W(q_2)$$

Where

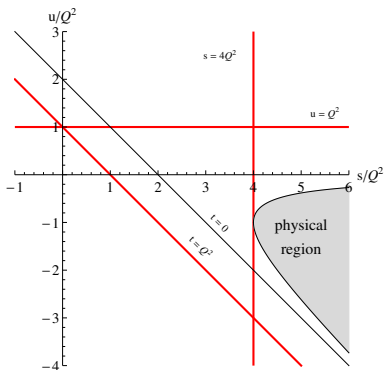
$$p_1^2 = p_2^2 = 0, \quad q_1^2 = q_2^2 = m^2$$

and the **kinematics** is:

$$s = (p_1 + p_2)^2 > 4m^2, \quad t = (p_1 - q_1)^2 < 0, \quad u = (p_2 - q_1)^2 < 0$$

$$s + t + u = 2m^2.$$

The two masses generate a more complicated cut structure  
(*even if their value is the same!*):



Same number of scales but cuts are together **linear** and **non-linear**

## Linearity + non-linearity $\rightarrow$

1. It is not possible to find a set of variables where all cuts are **linear functions**.
2. Parametrizing with

$$s = m^2 \frac{(1+x)^2}{x}, \quad u = -m^2 z, \quad \rightarrow \quad 0 < x < 1, \quad x < z < \frac{1}{x}.$$

One can nevertheless write everything in terms of **GHPLs!**

3. **Alphabet** is more complicated:

$$G(\vec{v}; x), \quad \text{with} \quad \vec{v} = \left\{ 0, 1, -1, i, -i, \frac{1+i\sqrt{3}}{2}, \frac{1-i\sqrt{3}}{2} \right\},$$

$$G(\vec{f}(x); z), \quad \text{with} \quad \vec{f}(x) = \left\{ 0, -1, x, \frac{1}{x}, \frac{1+x^2}{x}, \frac{1+x+x^2}{x}, \frac{x}{1+x+x^2} \right\}$$



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$$G(\vec{f}(x); z), \quad \text{with} \quad \vec{f}(x) = \left\{ 0, -1, x, \frac{1}{x}, \frac{1+x^2}{x}, \frac{1+x+x^2}{x}, \frac{x}{1+x+x^2} \right\}$$

- ▶ Presence of **non-linear** indices connected with **complex** indices in the other variable.
- ▶ Notice that they are solutions of the equations

$$1 + x^2 = 0, \quad 1 + x + x^2 = 0.$$

- ▶ These indices make the **numerical evaluation** of these GHPLs much more complicated.

$$G(x, z) = \ln\left(1 - \frac{z}{x}\right) = \ln\left(\frac{z}{x} - 1\right) \pm i\pi, \quad \forall z > x$$

- ▶ We will need to take **limits** on these functions!

## “Golden” properties of GHPLs:

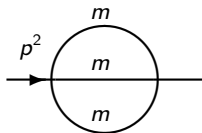
- ▶ They become easier under differentiation!
- ▶ If we differentiate enough times they become a **rational function!**
- ▶ Any properties of rational functions are **trivial!**
  1. If I know rational functions  $\rightarrow$  I know Logs
  2. If I know Logs  $\rightarrow$  I know di-Logs
  3. If I know do-logs  $\rightarrow$  I know tri-Logs...
- ▶ Any property of GHPLs can be proved **by differentiating enough times**

# Special Functions 2.

Elliptic functions

GHPLs are not the end of the story !

1. Massive two-loop Sunrise with **equal masses**



2. **two-scales:**  $p^2, m^2$
3. It should be function of **one variable**, say  $z = -p^2/m^2$ .
4. **HPLs** are unfortunately **not enough** !

**Imaginary part** of this graph comes from **Cutkosky-Veltman** rule:

$$\text{Im} \left( \text{---} \begin{array}{c} m \\ \circ \\ m \\ \text{---} \\ m \end{array} \right) \approx K(w^2) = \int_0^1 \frac{dx}{\sqrt{(1-x^2)(1-w^2x^2)}}.$$

where  $K(w^2)$  is the **complete elliptic integral of the first kind** and

$$w^2 = \frac{(E+m)^3(E-3m)}{(E-m)^3(E+3m)}, \quad E = \sqrt{p^2}$$

*(Exactly true in  $d = 2$ , almost the same in  $d = 4$ ...)*

Given the imaginary part we can write a dispersion relation:

$$\begin{aligned} S(p^2) &\approx \int_{s_0}^{\infty} \frac{du}{u - p^2 - i\epsilon} \text{Im}(S(u)) \\ &\approx \int_{s_0}^{\infty} \frac{du}{u - p^2 - i\epsilon} K(w^2(u)) \quad \rightarrow \quad ??? \end{aligned}$$

There are 3 kinds of **complete elliptic integrals**

1.

$$K(w^2) = \int_0^1 \frac{dx}{\sqrt{(1-x^2)(1-w^2x^2)}}$$

2.

$$E(w^2) = \int_0^1 dx \frac{\sqrt{(1-w^2x^2)}}{\sqrt{(1-x^2)}}$$

3.

$$\Pi(n; w^2) = \int_0^1 \frac{dx}{(1-nx^2)\sqrt{(1-x^2)(1-w^2x^2)}}$$

with

$$0 < w^2 < 1, \quad 0 < n < 1.$$



It is easy to show that any integral of the form:

$$\mathcal{I}(a_0, a_1, a_2, a_3) = \int_0^1 dx \frac{x^{a_0}}{(1 - nx^2)^{a_1} \sqrt{(1 - x^2)^{a_2} (1 - w^2 x^2)^{a_3}}},$$

can be written as linear combination of the three **master integrals**:

$$K(w^2), \quad E(w^2), \quad \Pi(n; w^2).$$

plus *Elementary Functions...*

Problem with elliptic functions is that  
**they do not get easier under differentiation!**

$$\frac{d}{dw^2} K(w^2) = \frac{1}{2w^2} \left[ \frac{E(w^2)}{1-w^2} - K(w^2) \right]$$

*differentiating an elliptic function we get again elliptic functions!*

Because of this reason a **iterated-integral** representation is not known...

Still much to do on elliptic functions...