## Dynamical Decoupling Applied to Polarization Qubits

#### BHASKAR ROY BARDHAN

#### QUANTUM SCIENCE & TECHNOLOGIES GROUP LOUISIANA STATE UNIVERSITY, USA



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# Outline

- Dynamical Decoupling (DD)-Introduction.
- Group theoretic interpretation of DD.
- Different DD Schemes-PDD, CDD, UDD, QDD.
- DD applied to polarization qubits in optical fiber.
- Results and Discussion.
- Summary.

# DD-General Idea

- Motivation: To protect the qubit in presence of decoherence.
- Applying pulses to time-reverse the system-bath interaction.
- A pulse producing a unitary evolution P, such that  $PH_{SB} P^{\dagger}=-H_{SB}$ , i.e. {P,  $H_{SB}$ }=0

# **Suppression of Decoherence**



One cycle

For ideal (zero-width) pulses

$$\begin{split} & \operatorname{Pexp}(-\mathrm{i}\tau H_{SB}) \mathrm{P}^{+} \mathrm{exp}(-\mathrm{i}\tau H_{SB}) = \\ & \operatorname{exp}(-\mathrm{i}\tau \mathrm{P} H_{SB} \mathrm{P}^{+}) \operatorname{exp}(-\mathrm{i}\tau H_{SB}) \\ & = \operatorname{exp}(\mathrm{i}\tau H_{SB}) \operatorname{exp}(-\mathrm{i}\tau H_{SB}) \\ & = \mathrm{I} \end{split}$$

Quick Example: Pure dephasing->H<sub>SB</sub>=λZ⊗B



One cycle

XZX=-Z=> "time-reversed", H<sub>SB</sub> averaged to zero (in 1<sup>st</sup> order Magnus expansion)

H<sub>SB</sub> = System-Bath Interaction P = Pulse(typically π pulses)

# **Effective Hamiltonian**

Another view of the universal decoupling sequence:



But, errors accumulate...:  $H_{eff}(T) \neq 0$ 

### DD AS SYMMETRIZATION

"Symmetrizing group" of pulses  $\{g_i\}$  and their inverses are applied in series:

$$(g_N^{\dagger} \mathbf{f} g_N) \cdots (g_2^{\dagger} \mathbf{f} g_2) (g_1^{\dagger} \mathbf{f} g_1) \approx \exp(-i\tau \sum_i g_i^{\dagger} H_{SB} g_i)$$
$$\mathbf{f} = \exp(-iH_{SB}\tau)$$

first order Magnus expansion

Choose the pulses so that:

$$H_{SB} \mapsto H_{eff}^{(1)} \equiv \sum_{i} g_{i}^{\dagger} H_{SB} g_{i} = 0$$

Dynamical Decoupling Condition

For a qubit the Pauli group  $G=\{X,Y,Z,I\}$  ( $\pi$  pulses around all three axes) removes an arbitrary  $H_{SB}$ :

(XfX) (YfY) (ZfZ) (IfI) = XfZfXfZf

Periodic DD: periodic repetition of the universal DD pulse sequence

# DD as a Rescaling Transformation $J = \|H_{SB}\|_{\infty}$

- $\beta = \|H_B\|_{\infty}$
- Interaction terms are rescaled after the DD cycle

 $J = J^{(0)} \mapsto J^{(1)} \propto \max[\tau(J^{(0)})^2, \tau\beta J^{(0)}]$ 

 $\beta \mapsto \beta + O((J^{(\mathbf{0})})^3 \tau^2)$ 

We need a mechanism to continue this

Periodic Dynamical Decoupling PDD Strategy: repeat the basic XfZfZfXfZ cycle with total of N pulses. The total duration is fixed at T. N can be changed. Pulse interval:  $\tau = T/N$ 

Recall noise strength  $\eta \equiv ||H_{eff}(T)||T$ norm of final effective system-bath Hamiltonian times the total duration.

PDD leading order result for error:

$$\eta \propto N^{-1}$$

Can we do better?

#### Concatenated Universal Dynamical Decoupling

Nest the universal DD pulse sequence into its own free evolution periods **f** :

p(1) = X f Z f X f Z f p(2) = X p(1) Z p(1) X p(1) Z p(1)p(n+1) = X p(n) Z p(n) X p(n) Z p(n)

Level	Concatenated DD Series after multiplying Pauli matrices
1	XfZfXfZf
2	fZfXfZfYfZfXfZffZfXfZfYfZfXfZf
3	Xf2fXf2fYf2fXf2ff2fXf2fYf2fXf2f2f2f2f2f2

Length grows exponentially; how about error reduction?

# Performance of Concatenated Sequences

error  $\mapsto$  (error)<sup>2</sup>  $\mapsto$  ((error)<sup>2</sup>)<sup>2</sup>  $\mapsto$  (((error)<sup>2</sup>)<sup>2</sup>)<sup>2</sup>  $\mapsto$   $\underset{k}{\dots}$   $\mapsto$  (error)<sup>2k</sup>

For fixed total time  $T-N\tau$  and N zero-width (ideal) pulses:

$$\eta \propto N^b N^{-c\log N}$$

Compare to periodic DD:

$$\eta \propto N^{-1}$$

# PDD vs. CDD

• CDD outperforms PDD for the bounded bath with *super-polynomial* 

advantage.

- In PDD, errors accumulate if not removed in the basic cycle.
- While in CDD, the next-layer-up removes the errors left from the last layer.
- Particularly important up to the 2<sup>nd</sup> order errors in the Magnus expansion

### Better Than Concatenated DD

Question

Does there exist an *optimal* pulse sequence?

Optimal-> removes maximum decoherence with least possible number of pulses.

# Uhrig Dynamical Decoupling

- Optimization of the switching instants.
- Good for *pure dephasing* as originally proposed by Uhrig.
- Requires O(n) number of pulses.
- Cycles with n pulses are used with the pulses applied at

 $\delta_j = Tsin^2[j\pi/(2n + 2)]$ 

#### Spin- Boson Model with Pure Dephasing

$$H = \sum_{i} \omega_{i} b_{i}^{\dagger} b_{i} + \frac{1}{2} \sigma_{z} \sum_{i} \lambda_{i} (b_{i}^{\dagger} + b_{i}) + E$$

 $\boldsymbol{\boldsymbol{\diamond}}\{\lambda_{i,}\ \omega_{i}\}$  – Properties of the bath

\*Spectral density 
$$J(\omega) = \sum_{i} \lambda_i^2 \delta(\omega - \omega_i).$$

**Free induction decay**  $e^{-2\chi(t)}$  where the decoherence function

$$\chi(t) := \int_0^\infty \frac{S(\omega)}{\omega^2} |y_n(\omega t)|^2 d\omega.$$
$$S(\omega) := \frac{1}{4} J(\omega) \coth(\beta \omega/2)$$

 $y_n$ - > Filter function for n pulses.

#### **UDD Continued:**

#### \* Aim: We have to minimize $\chi$ .

 $e^{-2\chi(t)} \sim 1$  when  $\chi$  (t) is written in powers of t.



Analytically shown first n derivatives of y<sub>n</sub>(ωt) = 0 at ωt = 0 for n pulses.



#### Quadratic Dynamical Decoupling (QDD) [West, Fong and Lidar 2010]

- One UDD sequence in one direction nested within another UDD sequence in an orthogonal direction.
- X-type UDD sequence (for pure dephasing) with a Z-type UDD sequence (for longitudinal relaxation).
- Relative sizes of the pulse intervals are considered

$$s_j = \frac{t_j - t_{j-1}}{t_1 - t_0} = \sin\left(\frac{(2j-1)\pi}{2n+2}\right)\csc\left(\frac{\pi}{2n+2}\right),$$

Pulse intervals ~(n+1)<sup>2</sup> are required.

# QDD (Contd.)

- Total normalized time  $S_n \equiv \sum_{j=1}^{n+1} s_j = \frac{t_{n+1}}{t_1} = \csc^2\left(\frac{\pi}{2n+2}\right),$
- Z-type UDD<sub>n</sub>  $Z_n(\tau) \equiv Z^n U(s_{n+1}\tau) Z U(s_n\tau) \cdots Z U(s_2\tau) Z U(s_1\tau)$
- $U(s_j\tau)$  is replaced by time-scaled sequence  $X_n(s_j\tau)$ .



# DD with Polarization Qubits

### Motivation

- Wu and Lidar [2004] analytically showed `bang-bang' decoupling could be used to suppress dephasing in optical fibers.
- However, CPMG sequence has been shown to be very robust against a variety of dephasing and rotation errors.
- In the BB84 protocol, it is crucial to preserve the input polarized signals against decoherence effects through the fiber.

- L.A.Wu and D.A. Lidar, Phys. Rev. A 70, 062310 (2004).
- S. Meiboom and D. Gill, Rev. Sci. Instrum. 29, 688 (1958).

#### **Dynamical Decoupling with Polarization Qubits**



• Dephasing after a propagation length  $\Delta L$  is  $\Delta \varphi = (2\pi/\lambda)\Delta L \Delta n$ ;

 $\Delta n = Refractive index difference, \lambda=Wavelength in vacuum.$ 

- **CPMG** sequence implemented by half-wave plates along the fiber.
- Both  $\Delta L$  and  $\Delta n$  were generated randomly to simulate the random dephasing.

# DD Preserves the Polarization State



Fidelity increases significantly when we apply DD in the fiber, even when the fluctuations in  $\Delta \phi$  are high.

# Contour plot of fidelity



# Estimating Minimum Number of Waveplates



• Equivalently, the **optimal distance between the waveplates** can be estimated for a given length of the fiber.

#### Fidelity for Different Fiber Lengths



• For a fixed range of  $\Delta \phi$  variation (i.e. fixed standard deviation  $\sigma$  of  $\Delta \phi$ ), the fidelity varies when we change the total length of the fiber. Mean value of  $\Delta L$ 

• **Dimensionless** :  $\Delta \phi = (2\pi/\lambda) \Delta L \Delta n = [(2\pi/\lambda) \Delta n < \Delta L>][\Delta L/<\Delta L>] => any fiber length can be used.$ 



- We could successfully apply the CPMG sequence to the optical fiber with flying polarization qubits.
- Waveplate seperation for achieving fidelity close to 1 could be estimated precisely for any arbitrary and practical fiber length.
- This is valid for any general polarization qubit.
- In future, we wish to incorporate finite width of the waveplate as well as use DD within gates for polarization qubits.

# Thank You